Size 23 Incremental Rotary Actuator

Design Description

Sierra Nevada Corporation's (SNC) Space Systems has designed, developed, and delivered an incremental actuator configured around a Size 23 hybrid stepper motor and a 10:1 planetary gearhead, providing output step resolution of 0.18° per motor step. The Size 23 Rotary Actuator was originally developed and qualified for a solar array drive application but is useful for any open-loop stepper motor driven system that needs fine incremental motion but can tolerate a small amount of backlash

SNC's Size 23 actuator is composed of a 2-phase, bipolar, 1.8-degree hybrid stepper motor with redundant windings that are insulated from one another to prevent failure propagation. The motor is directly coupled to a 10:1

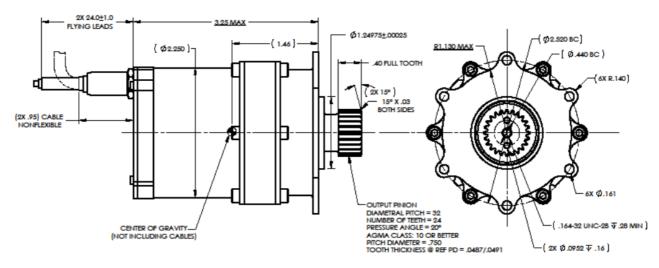


Size 23 Incremental Rotary Actuator

planetary gear reducer which features high strength and low backlash. The motor can be provided without the planetary stage and has a detachable shaft so that it can be mated to a different transmission or used as a direct drive motor. The output shaft can be provided with a spur gear, splined interface or other configuration. The redundant motor leads exit through the rear of the motor in two locations and are continuously shielded from the housing to the ends of the cables.

Fea	ntures			
•	High torque density, 2-phase, 1.8° hybrid stepper motor	•	Removable transmission assembly	
•	Redundant stator windings	•	Replaceable motor shaft extension	
•	10:1 low-backlash, high strength planetary gear set	•	Fully shielded flying lead cabling	

Dimensions



Note: All dimensions above are in inches.

Applications	ons			
Solar array drives	Antenna gimbals			

Не	ritage Programs	
•	Qualified but not yet flown for a SADA application	

	U.S.	SI	
Mechanical			
Actuator size (OD x L)	Ø2.8 in x 4.5 in	Ø71.1 mm x 114.3 mm	
Actuator mass	2.0 lb	0.9 kg	
Motor mass	1.3 lb	0.6 kg	
Output Torque, maximum	58.0 in-lb	6.6 Nm	
Step size	0.18° with gearhead, 1.8° without gearing		
Backlash	0.2° typical, 0.4° max.		
Electrical			
Motor type	2-phase, bipolar, redundant, 1.8° stepper		
Voltage, nominal	28 Vdc		
Resistance (at ambient temperature)	120 Ω		
Driver type	2-phase, bipolar (or 4-phase unipolar with reduced torque)		
Qualified Environments			
Random vibration	10.5 grms; 180 s / axis		
Sine vibration	13.0 g; 2 octaves / min / axis		
Pyrotechnic shock	1,865 g; 3 events / axis		
Temperature, operating	-4 °F to +176 °F	-20 °C to +80 °C	
Temperature, survival	-40 °F to 185 °F	-40 °C to +85 °C	

